

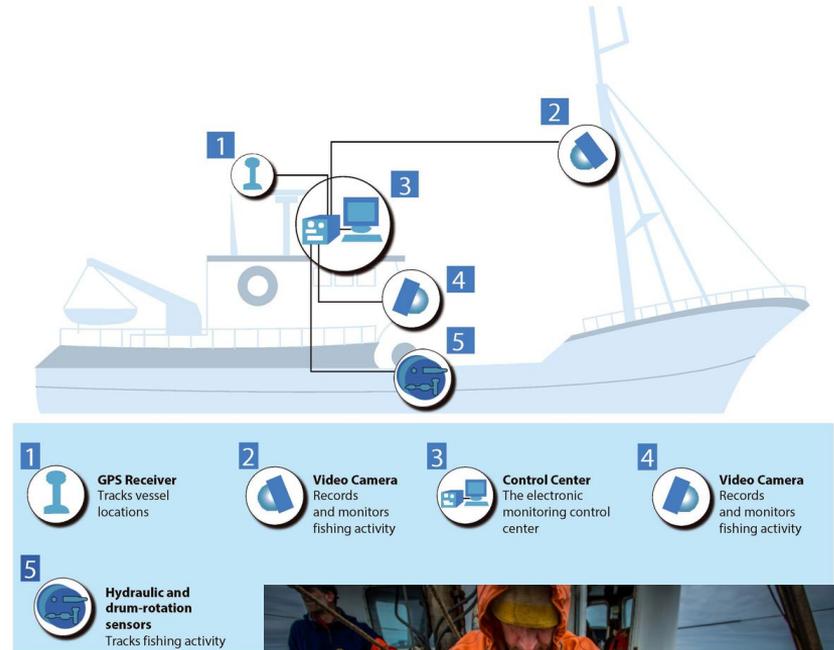
**Automated Fish Analysis in the Northeast Groundfish
Fishery: *Building a Library for Image Processing and
Machine Learning to Support Electronic
Monitoring Programs***

Ben Woodward



What Do We Mean by EM?

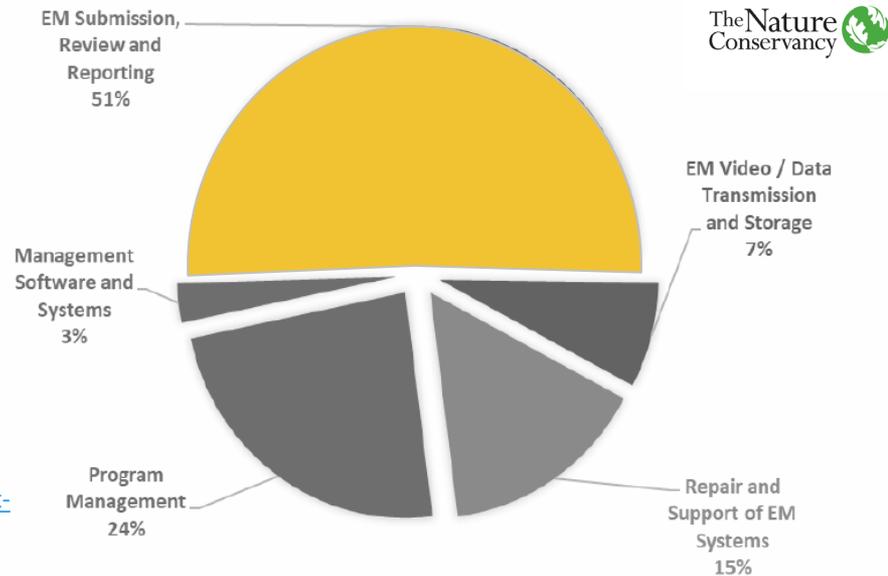
- **Electronic Monitoring (EM)** refers to the use of cameras and other sensors to monitor fishing activities
- Increase of the efficiency of fisheries monitoring
 - Reduced cost
 - Increased flexibility for fishers
 - More rapid data transmission
- Can generate large volumes of video data
- Natural fit for machine learning and automated image processing



Need for Means to Increase Efficiency

- Currently video review is the largest component of EM program costs
- Much of this involves simple species identification and length estimate generation
- Video review is an area project partners expect efficiencies can be developed

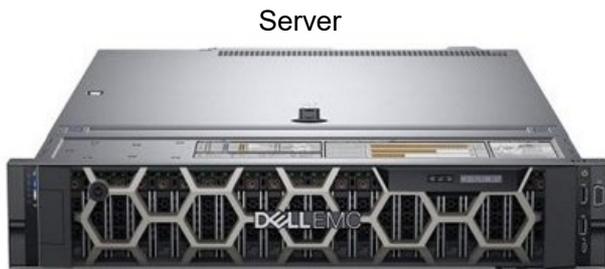
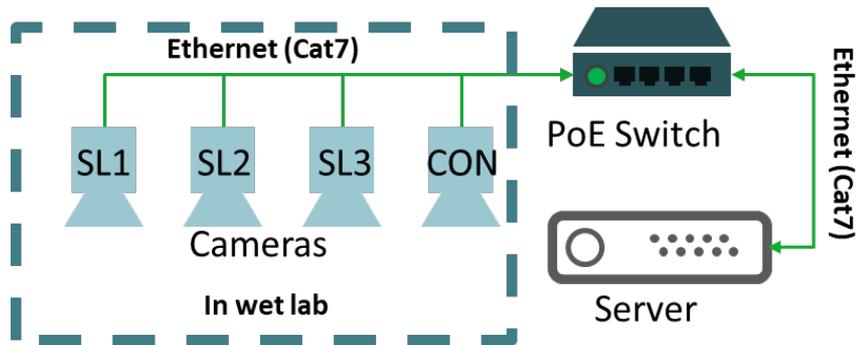
Chart 1: % of Annual Costs by Budget Category (Year 3 of Program)



https://eminformation.com/wp-content/uploads/2019/04/TNC-EM-Cost-Assessment-Report-Submission-to-NEFMC-4_10_19.clean_.pdf

Cap Logg Group LLC & The Nature Conservancy

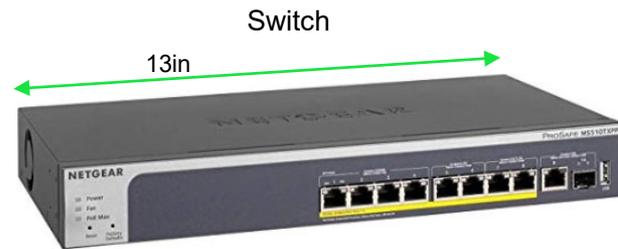
System Overview



Server

10GigE ethernet
32 TB RAID 10
24 core AMD EPYC
32 GB RAM

17.5in



Switch

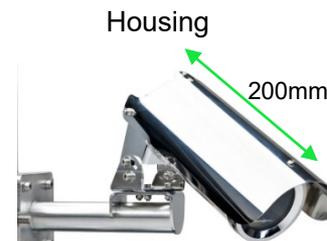
13in



Sensor



Lenses

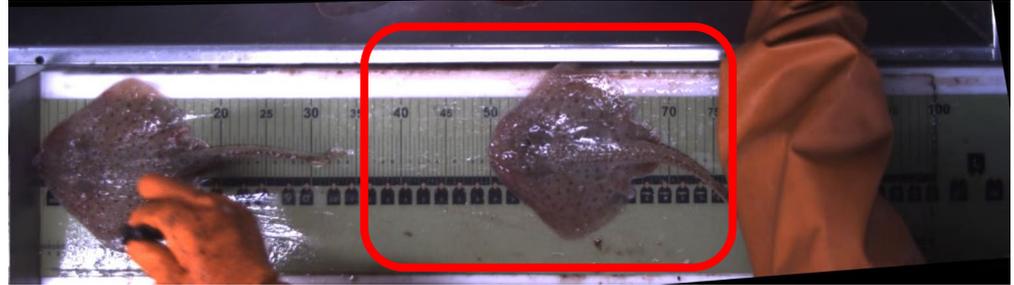


Housing

200mm

Capturing images on the boards

- Crew handling was **not** modified
- Two people at each station
- One person measuring and dissecting
- Another doing data entry
- Thus, for many individuals the clearest images are coming from the center of the of the board

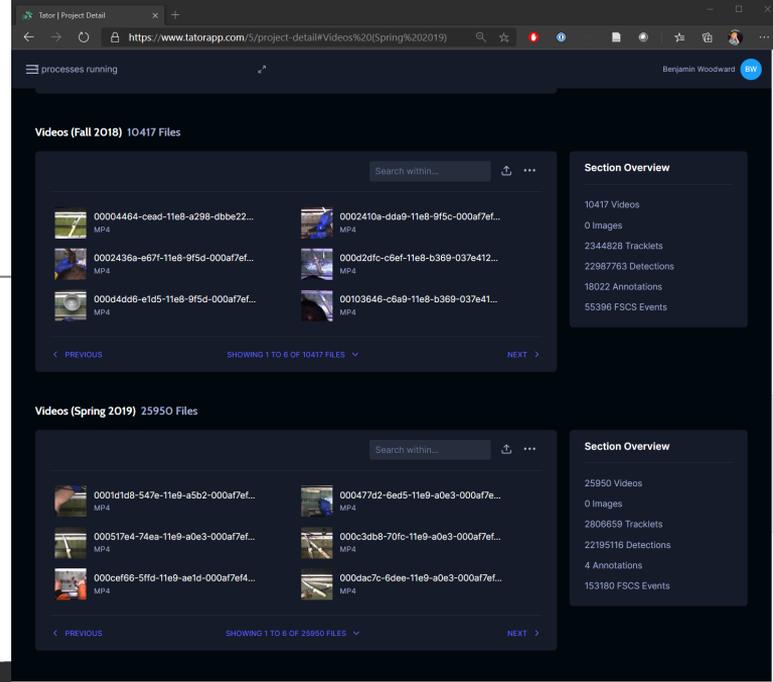


‘on deck’ position 

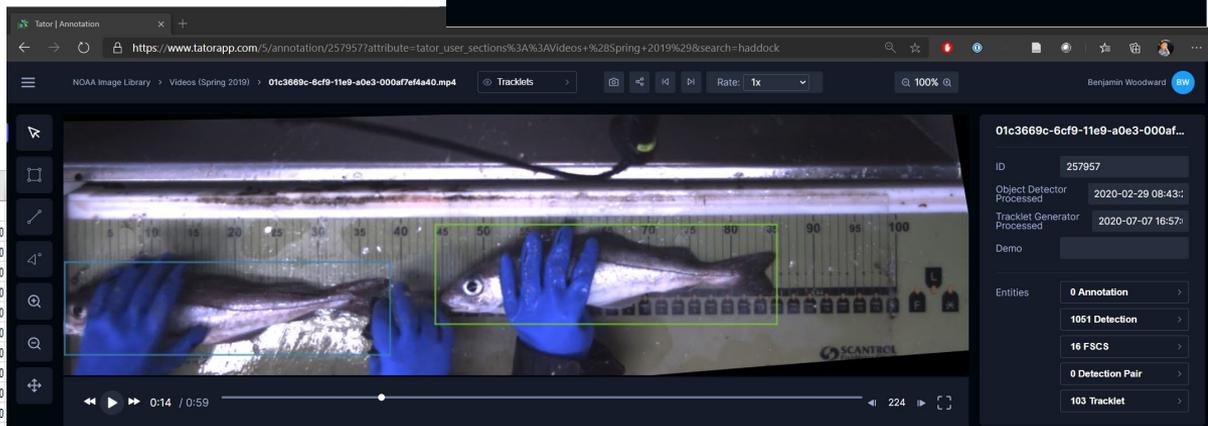


Tator Online – Collaborative Annotation and Analysis of Image and Video

- Web based platform for video/imagery annotation and analysis
- Open source project supported by CVision, NGS, and NOAA SBIR (<https://github.com/cvisionai/tator>)
- Customizable metadata, including hierarchical taxonomies (e.g. WoRMS, ITIS)
- Automated summary reports
- Custom algorithm pipelines for automated analysis and review within platform
- Used to make contributing material for other image libraries
 - FathomNet – MIT/MBARI/CVision
 - Fishnet.ai - TNC



	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P
1	section	media	thumbnai id	user	frame	type	x	y	width	height	Notes	Tentative Taxonomi	Species		MaxN	
2	Solomon	DOEX0015_20150111	7217014	Sarah Bingo	12275	box	0	934.5516	244.6917				Squalidae		0	
3	Solomon	DOEX0015_20150111	7217018	Sarah Bingo	15926	box	366.0237	12.99248	423.4179	367.0376			Squalidae		0	
4	Solomon	DOEX0015_20150111	7217019	Sarah Bingo	16541	box	538.2064	2.165414	525.2115	404.9323			Squalidae		0	
5	Solomon	DOEX0015_20150111	7217012	Sarah Bingo	9244	box	533.8748	0	210.0846	106.1053			Squalidae		0	
6	Solomon	DOEX0015_20150111	7217017	Sarah Bingo	15731	box	225.2453	0	1038.511	415.7594			Squalidae		0	
7	Solomon	DOEX0015_20150111	7217020	Sarah Bingo	16788	box	136.4467	28.15038	1012.521	395.188			Squalidae		0	
8	Solomon	DOEX0015_20150111	7217011	Sarah Bingo	9244	dot	663.824	58.46617	0	0			Selachii		0	
9	Solomon	DOEX0015_20150111	7217055	Sarah Bingo	9120	dot	492.7242	470.9774	0	0			Actinopterygii		0	
10	Solomon	DOEX0015_20150111	7217013	Sarah Bingo	12267	dot	468.9002	85.53383	0	0			Squalidae		0	
11	Solomon	DOEX0015_20150111	7217010	Sarah Bingo	0	dot	868.5037	55.01976	0	0	seafloor arrival; hard bottom		none		0	

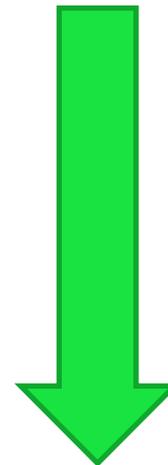


Hierarchy of Video Analysis Automation

- Object Localization – I saw a fish here
 - Count of all fish in a frame

- Object Classification – I saw this kind of fish
 - Count of different types of fish in a frame

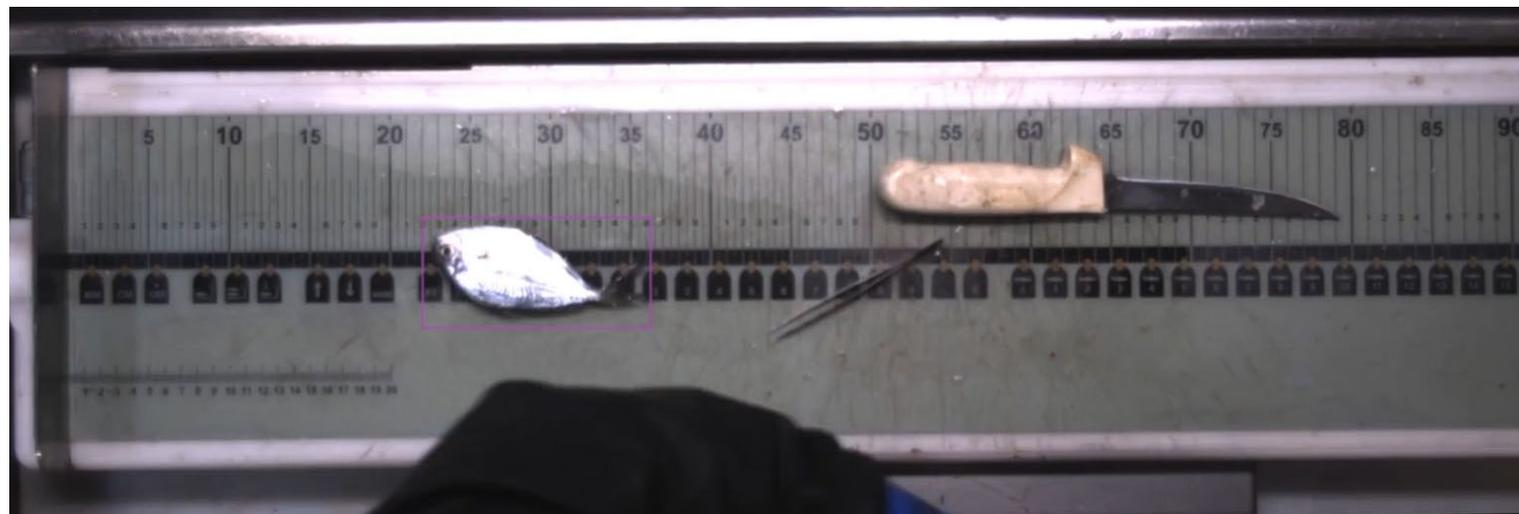
- Multi-Object Tracking – I saw this individual fish
 - Count of all fish of different species in a video



- Increasing Automation
- Increasing Difficulty

Every step in the hierarchy to be automated reduces the review burden on human analysts

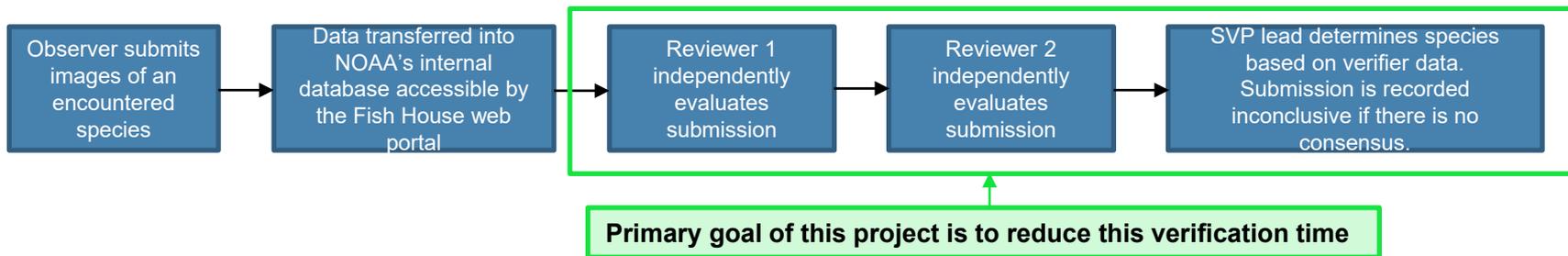
High Count Matching



Species Verification Project

- Northeast Fisheries Observer Program (NEFOP) observers required to submit species encountered on fishing operations
 - Fisheries Sampling Branch (FSB) observer programs utilizes this accurate and near real-time data collection for quota and population monitoring
- Species Verification Program (SVP) goals:
 - Ensure high levels of species identification accuracy by verifying submissions of observed species
 - Inform observers about identification issues and improve training methods

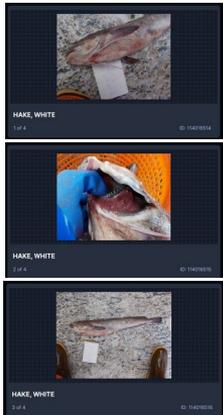
Species Submission Verification Process



Algorithm pipeline

SVP Submission

Media:SVP_IDNUM == 137334 x



Submission image(s)

Whole-body fish detector

Creates detections (bounding boxes) on whole-body species

Detections with confidence scores



Image Filter

Select images with a single detection whose confidence \geq threshold (0.4 was used)

If no images match the above criteria, use entire submission image set

Full image(s) with valid detection criteria



Image classifier

Run classifier on valid image set

Classifier Filter

Select classifier result with lowest entropy. Provide top 3 labels or UNKNOWN if above entropy threshold

- Top 3 Labels:
- HAKE, WHITE
 - HAKE, RED (LING)
 - HAKE, SPOTTED



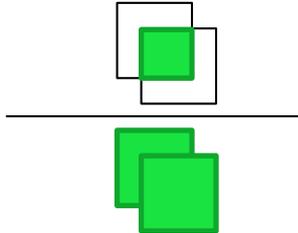
Object Detector Performance

- Performance reported in HTML report
- Whole-body vs partial-body image:
 - If detector created 0 detections, assume partial-body image
 - Otherwise, assume a whole-body image
- Metrics based on whole-body vs partial-body image identification
 - Precision
 - How often does the detector incorrectly predict a partial-body image as a whole-body image
 - Recall
 - How often does the detector incorrectly predict a whole-body image as a partial-body image
 - Intersection over union
 - How well does the detector's bounding box compare with the annotated truth

Detector Performance Metrics

$$Precision = \frac{\# \text{ of correct whole body predictions}}{\# \text{ of correct whole body predictions} + \# \text{ of incorrect partial predictions}}$$

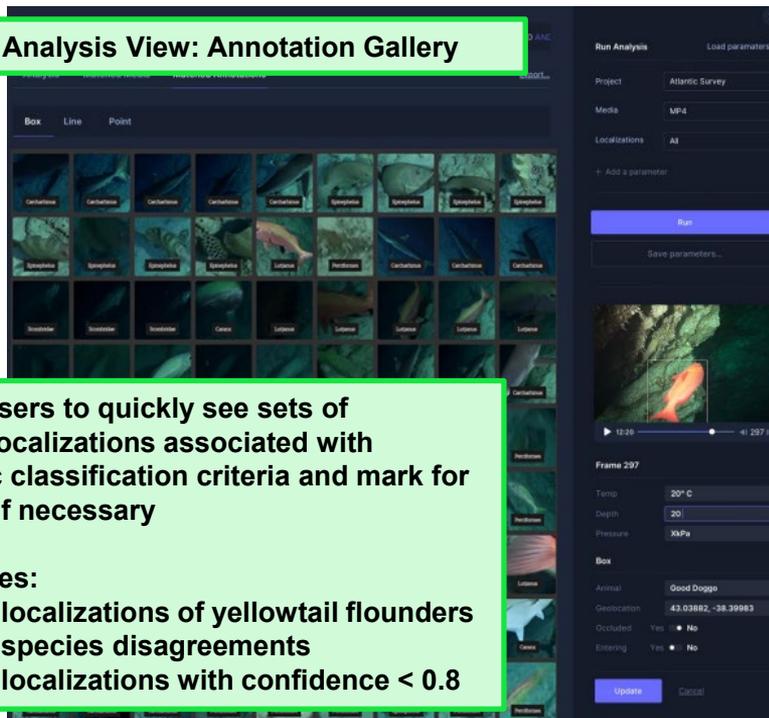
$$Recall = \frac{\# \text{ of correct whole body predictions}}{\# \text{ of correct whole body predictions} + \# \text{ of incorrect whole body predictions}}$$

$$IoU = \frac{Intersection}{Union}$$


The diagram shows two overlapping green squares representing bounding boxes. A horizontal line is drawn across the middle of the squares, separating the top square from the bottom square. The top square is partially overlapping the bottom square, and the bottom square is also partially overlapping the top square. This visualizes the concept of Intersection over Union (IoU), where the intersection is the area where the two squares overlap, and the union is the total area covered by both squares.

Tator: Analysis View

Analysis View: Annotation Gallery



Run Analysis Load parameters...

Project Atlantic Survey

Media MP4

Localizations All

Run

Save parameters...

Frame 297

Temp 20° C

Depth 20

Pressure XPa

Box

Animal Good Doggo

Geolocation 43.03882, -38.39983

Obscured Yes No

Entering Yes No

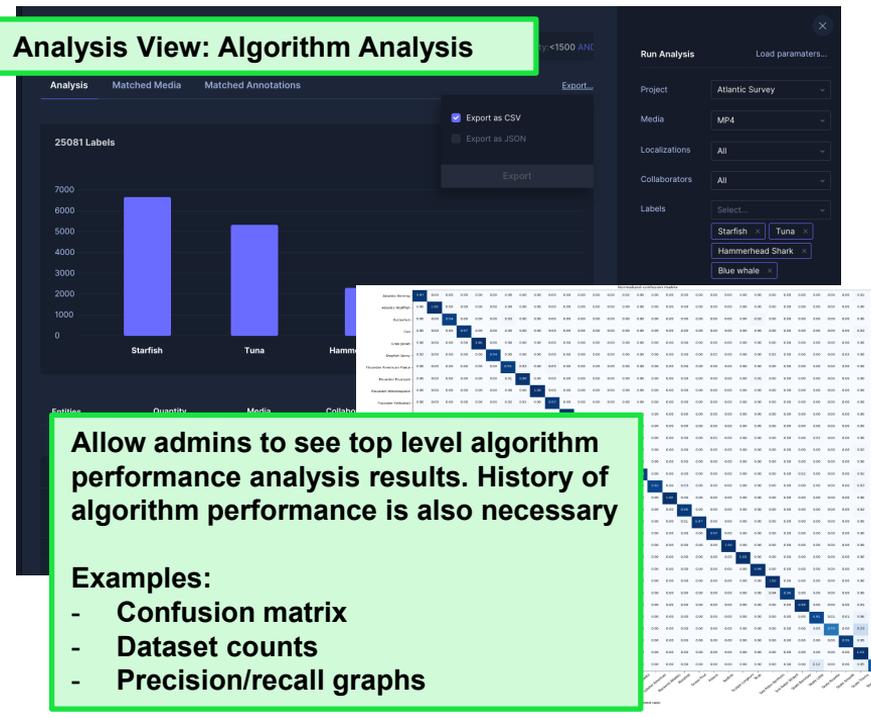
Update Cancel

Allow users to quickly see sets of media/localizations associated with specific classification criteria and mark for review if necessary

Examples:

- See localizations of yellowtail flounders
- See species disagreements
- See localizations with confidence < 0.8

Analysis View: Algorithm Analysis



Run Analysis Load parameters...

Project Atlantic Survey

Media MP4

Localizations All

Collaborators All

Labels

Select...

Starfish Tuna

Hammerhead Shark

Blue whale

Export...

Export as CSV

Export as JSON

Export

25081 Labels

7000

6000

5000

4000

3000

2000

1000

0

Starfish Tuna Hammerhead Shark

Entities Quantity Media Collaborators

Confusion Matrix

Allow admins to see top level algorithm performance analysis results. History of algorithm performance is also necessary

Examples:

- Confusion matrix
- Dataset counts
- Precision/recall graphs



Thank You! – Support From Many Sources Made These Projects A Success

- **Henry B. Bigelow crew** for support at sea
- **ESB Staff** supported work at sea and FSCS data requests
- **Brett Alger, Andy Jones, Glenn Chamberlain, and Chris McGuire** contributed ideas and advice
- The **FIS** and **NOP** provided funding for this project

From Imagery To Insights
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